

Timer Control for Triac and Relay

Description

The timer control circuit, U2100B, uses bipolar technology. It has different mode selections (Zero voltage switch, Phase control, Relay control). The output stage is

triggered according to input conditions. It can be used in triac application for two or three wire system as a power switch.

Features

- Adjustable and retriggerable tracking time
- Window monitoring for sensor input
- Enable input for triggering
- Internal noise suppression (40 ms) and retrigger blocking (640 ms)
- Two or three wire application

Package: DIP8, SO8

Applications

- Motion detectors
- Touch sensors
- Timer

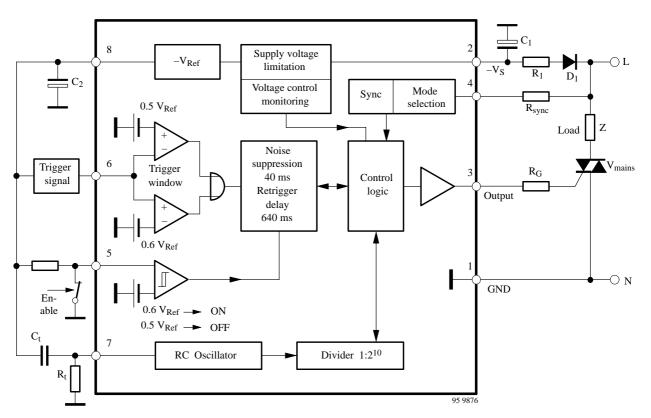
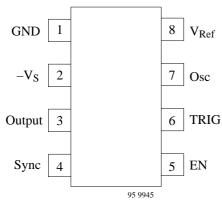


Figure 1. Block diagram with external circuit

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Pin Description



Pin	Symbol	Function		
1	GND	Reference point		
2	$-V_S$	Supply voltage		
3	Output	Driver output		
4	Sync	Synchronisation and mode selection		
5	EN	Enable		
6	TRIG	Input trigger signal		
7	Osc	RC Oscillator		
8	V _{Ref}	Reference voltage		

General Description

Monostable integrated power control circuit, U2100B, can be used according to mode selection in relay's or triac's applications. Beyond that, it can be used in triacapplication for two wire system as power switch, (being the load in series to the switch) whereas the supply voltage for the control unit is gained from phase rest angle (α_{min} -operation).

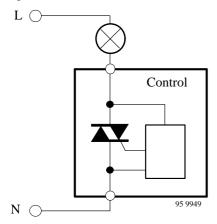


Figure 2. Two wire circuit

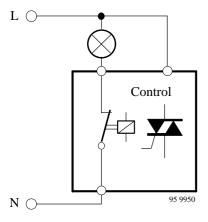


Figure 3. Three wire circuit

For three wire switch, two modes of operations are possible:

- Zero voltage switch operation for triac control
- Static operation for relay control

Mode Selection Pin 4 and Supply Voltage Pin 2

Operation modes can be selected by external voltage at the sync. input Pin 4 (clamping). Mode selection determines the current requirement of driver stage for relay's or triac's and hence the selection of supply voltage.

Zero Voltage Switch Operation, Figure 4

Selection condition:

 V_4 = internal sync limitation, without external clamping

$$R_1 \approx 0.85 \frac{V_{\text{M}} - V_{\text{S}}}{2 \text{ L}_{\text{tot}}}$$

$$I_{tot} = I_S + I_p + I_X$$

whereas:

I_S = Supply current of IC without load

 I_P = Average trigger current I_G

I_X = External circuit current requirement

 V_{M} = Mains voltage

Required firing pulse width tp

$$t_{p} = \frac{2}{\omega} \arcsin \left(\frac{I_{L} \times V_{M}}{P \times \sqrt{2}} \right)$$

whereas:

 I_L = Triac latching current

P = Power at load Z

$$R_{sync}[k\Omega] \approx \frac{V_{\text{M}}[V] \times \sqrt{2} \sin \left(\omega \times t_{\text{p}}[s]\right) - 0.7}{1.8 \, \times \, 10^{-2}} - 176$$

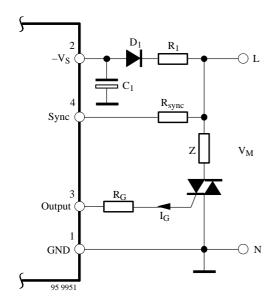


Figure 4.

α_{min} -Operation, Figure 6

Selection condition:

$$-V_4 = 6.5$$
 to 7.8 V $+V_4 = int$. limitation

$$R_{\alpha max} = R_{sync} \frac{3.6 \text{ V}}{V_{R(peak)} - 3.6 \text{ V}}$$

$$R_{\alpha min} = R_{sync} \frac{10 \text{ V}}{V_M \times \sqrt{2} - 10 \text{ V}}$$

 $V_{R(peak)}$ is the peak voltage of the rest phase angle, which should be high enough to generate the supply voltage, V_{S} .

DC Operation, Figure 5

Selection condition:

$$+V_4 = 6.1 \text{ V}$$
 $-V_4 = \text{int. limitation}$

whereas:

$$R_0 \approx 1/10 X_c$$

$$X_c = 0.85 \frac{V_M - V_S}{I_{tot}}$$

$$I_{tot} = I_S + I_{Rel} + I_X$$

$$C_0 = \frac{1}{\omega \times X_C}$$

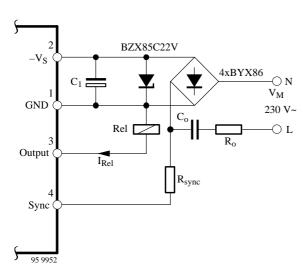


Figure 5.

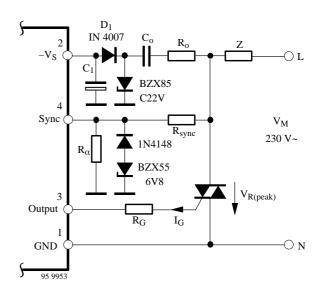


Figure 6.

 $\begin{array}{lll} C_1 & = & 100 \, \mu F/35 \, V \\ C_o & = & 0.33 \, \mu F/250 \, V \sim \\ R_o & = & 390 \, \Omega \\ R_{sync} & = & 220 \, k\Omega \\ R_\alpha & = & 10 \, k\Omega \\ R_G & = & 390 \, \Omega \\ D_1 & = & IN \, 4007 \end{array}$

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Tracking Time Pin 7

An internal RC oscillator with following divider stage 1:2¹⁰ allows a very long and reproducible tracking time.

RC-values for required final time, t_t , can be calculated as follows:

$$R_{t}[\Omega] = \frac{t_{t}[s] \ 10^{6}}{1.6 \ 1024 \ C_{t}[\mu F]}$$

$$C_{_t}[\mu F] \, = \frac{t_t[s] \ 10^6}{1.6 \ 1024 \ R_t[\Omega]} \label{eq:ct}$$

$$t_{\scriptscriptstyle t} \; [s] = \frac{C_{\scriptscriptstyle t} [\mu F] \times R_{\scriptscriptstyle t} [\Omega] \times 1.6 \times 1024}{10^6} \label{eq:tt}$$

Trigger Inputs Pins 5 and 6, Figures 7 and 8

Two AND-connected, identical inputs determine the trigger conditions of monostable time stages, i.e., both inputs must be in position "ON" so that the output is switched ON. The tracking time starts after the trigger conditions has elapsed. The output ON state is given until the tracking time is over.

Input Pin 5 is a simple comparator whereas input Pin 6 is built up as a window discriminator.

Noise suppression for $t_{ON} = 40$ ms guarantee, that there is no peak noise signals at the inputs which could trigger the circuit.

At the same time, the retrigger is delayed for a duration of 640 ms (t_{OFF}), to avoid noise signal to trigger the relay.

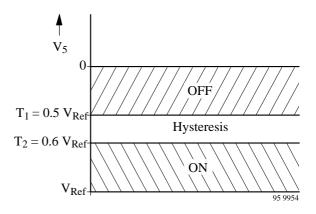


Figure 7. Trigger condition, Pin 5

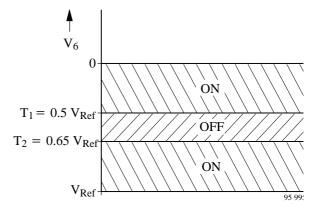


Figure 8. Trigger condition, Pin 6

Absolute Maximum Ratings

Reference point Pin 1, unless otherwise specified

Parameters	Symbol	Value	Unit	
Supply	Pin 2			
Supply current		-I _S	10	mA
Peak current $t \le 10 \mu s$		$-i_s$	60	mA
Supply voltage		$-V_{S}$	32	V
Reference voltage source	Pin 8			
Output current		I_{O}	3	mA
Synchronization	Pin 4			
Input current		±I _{Sync} .	5	mA
t ≤ 10 μs		i _{Sync} .	20	mA
Window monitoring				
Input voltage	Pin 6	$-V_1$	V _{Ref} to 0	V
Enable-Schmitt trigger	Pin 5			
Input voltage		$-V_1$	V _{Ref} to 0	V
Driver output	Pin 3			
Collector voltage		$-V_{o}$	V_S to 2	V
Storage temperature range		T _{stg}	-40 to +125	°C
Junction temperature		T_{i}	125	°C
Ambient temperature range	T _{amb}	0 to 100	°C	



Thermal Resistance

Parameters		Symbol	Value	Unit
Junction ambient	DIP8	R_{thJA}	110	K/W
	SO8 on PC board	R_{thJA}	220	K/W
	SO8 on ceramic	R_{thJA}	140	K/W

Electrical Characteristics

 $V_S = -18 \ V$, $T_{amb} = 25 ^{\circ} C$, reference point Pin 1, unless otherwise specified

Parameters	Test Conditions / Pins	Symbol	Min	Тур	Max	Unit	
Supply voltage limitation	$I_S = 800 \mu\text{A}$ Pin 2	$-V_S$	21		23	V	
	$I_S = 2 \text{ mA}$		21.3		24	V	
Current consumption	$I_3 = 0$	$-I_S$			750	μΑ	
Supply voltage monitoring	Pin 2	-		1		T	
ON-Threshold		$-V_{S}$		15		V	
OFF-Threshold		$-V_S$		6.5		V	
Reference voltage	$ I_8 = 0.1 \text{ mA} $ Pin 8 $ I_8 = 1.5 \text{ mA} $	$-V_{Ref}$	4.75 4.55		5.25 5.25	V V	
Synchronization	Pin 4						
Input current		± i _{sync}	0.1		1.1	mA	
Voltage limitation	$I_4 = \pm 1 \text{ mA}$	±V _{sync}	8.8	9.4	10	V	
Rest phase angle	ON	±V _T	3.6	4	4.4	V	
α_{min} -threshold	Off	$\pm V_{\mathrm{T}}$	1.8	2	2.2	V	
Zero-identification	Zero-identification Pin 4						
Zero-identification	ON	$\pm V_{\mathrm{T}}$		1.5		V	
		$\pm I_{\mathrm{T}}$		8.5		μA	
	OFF	$\pm V_{T}$		4		V	
0 " 1 "	D: 4	±Ι _Τ		20		μΑ	
Operation selection	Pin 4						
Zero voltage switch		±V _{sync}		V ₄ limit		**	
α_{\min} -operation		+V _{sync}		V ₄ limit 6.5 to 7.8		V	
DC mode		-V _{sync}		V ₄ limit		V	
DC IIIode		-V _{sync} +V _{sync}		6.5 to 7.8		V	
Window monitoring figure	4 Pin 6	· · · sync		0.5 to 7.0		1 ,	
Threshold 1		-V _I /V _{Ref}	0.52	0.49	0.46		
Threshold 2		$-V_{\rm I}/V_{\rm Ref}$	0.67	0.65	0.63		
Enable-Schmitt trigger	Pin 5	' F ' KUI	2.0,	2.50	2.02	1	
Threshold 1	OFF	-V _I /V _{Ref}	0.33	0.3	0.27		
Threshold 2	ON	$-V_{\rm I}/V_{\rm Ref}$	0.62	0.6	0.58		
Oscillator $f = \frac{1}{1.6 \times R_t \times C_t}$							
Threshold 1	Pin 7 – 1	V _I /V _{Ref}	0.25	0.20	0.15		
Threshold 2	Pin 7 – 8	V _I		100	200	mV	
Input current	Pin 7	I _I		100	500	nA	
Output stage limiter diode	e w.r.t. Pin 1 Pin 3	• 1					
Saturation voltage	$I_3 = 100 \text{ mA}$	V ₃₋₂			2	V	
Output current		I ₃	100			mA	



Applications

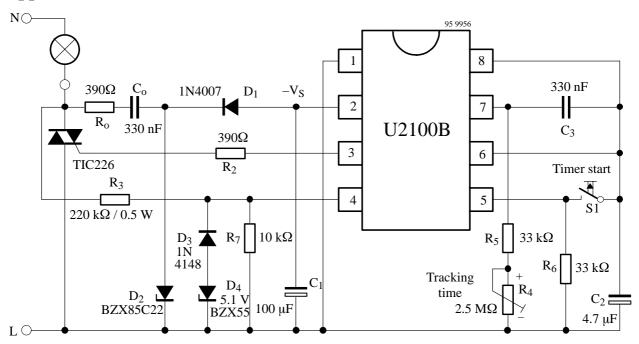


Figure 9. Lamp time control 18 sec. to 23 min. for two wire systems

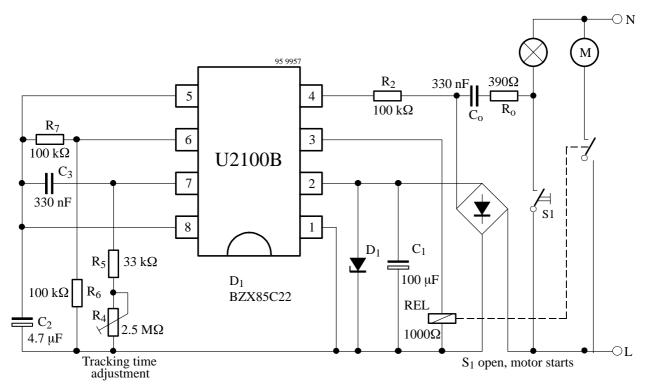
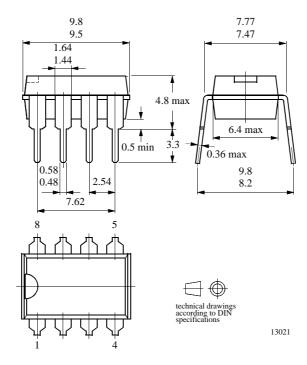


Figure 10. Fan tracking time control 18 sec. to 23 min.

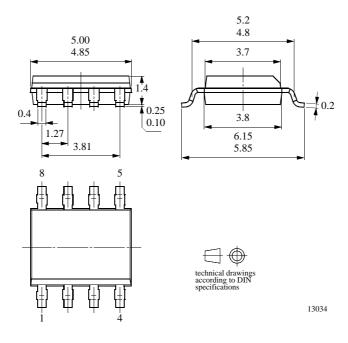


Package Information

Package DIP8
Dimensions in mm



Package SO8
Dimensions in mm



U2100B



Ozone Depleting Substances Policy Statement

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- 2. Regularly and continuously improve the performance of our products, processes, distribution and operating systems with respect to their impact on the health and safety of our employees and the public, as well as their impact on the environment.

It is particular concern to control or eliminate releases of those substances into the atmosphere which are known as ozone depleting substances (ODSs).

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TEMIC Semiconductor GmbH semiconductor division has been able to use its policy of continuous improvements to eliminate the use of ODSs listed in the following documents.

- 1. Annex A, B and list of transitional substances of the Montreal Protocol and the London Amendments respectively
- 2. Class I and II ozone depleting substances in the Clean Air Act Amendments of 1990 by the Environmental Protection Agency (EPA) in the USA
- 3. Council Decision 88/540/EEC and 91/690/EEC Annex A, B and C (transitional substances) respectively.

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TEMIC Semiconductor GmbH, P.O.B. 3535, D-74025 Heilbronn, Germany Telephone: 49 (0)7131 67 2831, Fax number: 49 (0)7131 67 2423

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